python 2-D: Computer vision

1. **2-d Data (Images):**

Images (and video) can be stored in a variety of formats. However, the most important distinction is between “compressed” and “raw” (uncompressed) data. Raw data can be loaded into system memory (RAM) by directly reading the stored bytes, whereas compressed images must first be decoded, a process which requires knowing how the image was encoded in the first place. Fortunately, many image reading functions handle the detection and application of the correct decoder for you, but it is important to understand what is happening. We will explore differences in compression techniques by loading, processing, and displaying the same image encoded with different methods.

Loading image data normally requires a special library that understands how to deal with image compression. There are many such libraries, and here we will be using OpenCV. *Make sure that you have OpenCV installed in your Python environment.*

# image processing

Let’s now try to open a random image. Open Spyder and let’s start writing our first Python+OpenCV program. Enter the following code into a new Python script.

# Import the OpenCV package

import cv2

### # Import the plotting package

import matplotlib.pyplot as plt

# Make a string that contains the file path of an image (explain r and filepath)

filename= r'C:/SomeImagePath\image.jpg’

#Load the image

image = cv2.imread(filename)

# Show image

plt.imshow (image)

# Save the image

cv2.imwrite(r'C:/SomeImagePath\new\_image.jpg’, image)

#FIN

### Exercise 3.1.1: binary image

* Add to the code above functions from the OpenCV library, to convert your image from colour to grayscale. Then, threshold the image thus converting it from grayscale to binary zero/one, and display the result.

### Exercise 3.1.2: coloured images

* Which function would you use in order to extract a selected object from a coloured image?

# **video processing**

It is very common to detect specific features/objects in a movie that are moving, i.e. changing in their intensity relative to static features. Therefore, many methods in computer vision have been developed to generate an estimate of the static scene, i.e. Bkg from which objects in the “foreground can be isolate. Most of these methods normally require having access to multiple images in which the object of interest is different locations. Therefore, to start developing methods to differentiate static vs dynamic images we must first lear how to load the frames of a video sequence

## Task 4.1: video processing

Videos can be encoded (compressed) in many different formats (mpeg, dvix, h.264 etc.). In order to read the data (decode) decompress video, Python/OpenCV requires the correct “codec” - a separate piece of software that can interpret a specific style of video compression. The appropriate codecis not always immediately accessible to Python/OpenCV. For example, and as we use below, the code for interpreting mpeg-h.264 (a very common video compression format) must be explicitly located in the main Python directory. [Yes, I know this is clunky, however, there is always something clunky, and overcoming these seemingly irrational obstacles to getting a computer program do what you want is often the main challenge. Google it or email it your former TAs! ].

# OpenCV.package

import cv2

import matplotlib.pyplot as plt

# Make a string that contains the file path of the movie

filename= r'C:/Users/Elena/Desktop/video.avi'

cap = cv2.VideoCapture(filename)

for i in range(0,2):

# Capture frame-by-frame

ret, frame = cap.read()

#Your algorithn goes in here!!

# Show result on a screen

plt.imshow(frame)

plt.draw()

plt.pause(0.001)

plt.clf()

cap.release()

#FIN

**Very Important:** In order to make Python/OpenCV aware of the “FFmpeg codec, copy the “…”opencv\_ffmpeg249\_64.dll” (this should be the path “opencv\build\x64\vc14\bin\ opencv\_ffmpeg249\_64.dll”) to the main Python directory (where the Python.exe is located; “C:\WinPython-64bit-4’’).

### Exercise 4.1.1: background

* Copy the code above and load one of the video you saved Yesterday.
* Now that you can load all the frames of a movie how would you go about computing the “background”, i.e. the intensity of each pixel in the static scene when there is nothing changing?
* One obvious approach is to just generate the average frame by selecting many frames across the movie where the object that is moving is in different locations. The code to do this is shown below. However this technique is not ideal. Why? What could you do to generate a more accurate estimate of the
* Ssssss

# OpenCV.package

import cv2

import matplotlib.pyplot as plt

import numpy as np

# Make a string that contains the file path of the movie

filename= r'C:/Users/Elena/Desktop/video.avi'

# It is the handle that gives you the location of the movie

cap = cv2.VideoCapture(filename)

#Get width and height properties of the image

width= cap.get(cv2.cv.CV\_CAP\_PROP\_FRAME\_WIDTH)

height= cap.get(cv2.cv.CV\_CAP\_PROP\_FRAME\_HEIGHT)

#Compute the background

Bkg= np.zeros((height,width,20))

Bkg\_count=0

for i in range (0,200,10):

# It sets in which position you are in the movie

cap.set(cv2.cv.CV\_CAP\_PROP\_POS\_FRAMES, i)

# It opens the frame of the movie located at the position defines above

ret, frame = cap.read()

gray\_frame = cv2.cvtColor(frame, cv2.COLOR\_BGR2GRAY)

# Sum of all the Bkg frames

Bkg[:,:,Bkg\_count]= gray\_frame

Bkg\_count=1+Bkg\_count

Bkg\_image = np.mean(Bkg, axis=2)

plt.imshow(Bkg\_image)

plt.draw()

cap.release()

#FIN

### Exercise 4.1.2: Better background

* Change the code above to generate and display a better estimate of the background

# **object tracking**

Tracking an object is a basic goal of computer vision and fundamental to many neuroscience experiments.The fundamental premise of tracking is to find a way to segment the object you want to track from the rest of the image, and then use operations on the binary image () to compute the location and other features of the object of interest (area, size, orientation, shaoe etc.).

It is often not possible to uniquely identify the pixels belonging to the desired object vs others often simply due to noise. Therefore, it is important in a tracking algorithm to be able to distinguish which grouping of foreground pixels is valid. (describe in better way binary code)

In OpenCV binary regions are located by founding contours, the boundary between background and foreground pixels. When connected contours have been detected, one can begin to measure several features of the region of interest (such as length, centroid, size, area), or to exclude, for example, contours that are too big or too small.

cap = cv2.VideoCapture(filename)

plt.figure()

for i in range(0,2000):

# Capture frame-by-frame

ret, frame = cap.read()

gray\_frame = cv2.cvtColor(frame, cv2.COLOR\_BGR2GRAY)

Bkg\_image=Bkg\_image.astype(np.uint8)

# SUBSTRACT THE BACKGROUND from the movie and make the absolute difference

Bkg\_Sub\_Frame=cv2.absdiff(Bkg\_image, gray\_frame)

# THRESHOLD the absolute difference movie

ret,thresholded\_frame = cv2.threshold(Bkg\_Sub\_Frame,5,255,cv2.THRESH\_BINARY)

Fish=np.copy(thresholded\_frame)

# Find all the particles as CONTOURS in the movie

Particle, hierarchy=cv2.findContours(thresholded\_frame, cv2.cv.CV\_RETR\_EXTERNAL,cv2.cv.CV\_CHAIN\_APPROX\_NONE)

# GET THE INDEX of BIGGEST particle

P\_size=np.zeros(np.size(Particle))

for p,idx in enumerate (Particle):

P\_size[p]= np.size(idx)

Big\_Particle=np.argmax(P\_size) # returns the index within P\_size array that contains the biggest particle

# Get the centroid of the biggets particle by making the average of the centroid coordinates

Particle\_CenroidXY=np.mean(Particle[Big\_Particle], axis=0)

# Show result on a screen

plt.imshow(Fish)

plt.plot(Particle\_CenroidXY[0,0],Particle\_CenroidXY[0,1],'o')

plt.draw()

plt.pause(0.001)

plt.clf()

cap.release()

Bonus Exercise 5.1.1: Try to get more information beyond the position of the object (area, orientation, shape)